

We have spent a lot of time discussing manifolds. In the last lecture we will briefly talk about topology. How do we distinguish manifolds from each other?

Differential forms can in fact help us answer this question.

### Poincaré lemma (§ 39)

$\omega \in \Omega^k(M)$ .

- Closed :  $d\omega = 0$
- exact :  $\exists \eta \in \Omega^{k-1}(M) : \omega = d\eta$ .

Clearly exactness  $\Rightarrow$  closedness :

$$d\omega = d(d\eta) = 0 \text{ because } d^2 = 0.$$

When is a closed form exact?

The answer turns out to be intimately connected with topology.

Def  $A \subset^{\text{open}} \mathbb{R}^n$ ,  $B \subset^{\text{open}} \mathbb{R}^m$

$g, h: A \rightarrow B$  smooth.

We say that  $g$  and  $h$  are homotopic if there's a smooth fun

$H: A \times [0,1] \rightarrow B$

s.t.  $H|_{A \times \{0\}} = g$ ,  $H|_{A \times \{1\}} = h$ .

---

Rmk: We think of the  $[0,1]$ -factor as being parametrized by time.

$H = H(x, t)$ , and at time  $t=0$  &  $t=1$  resp. we have the smooth maps  $g$  and  $h$ , resp.

For each  $t$  we have a smooth map

$$H_t: A \rightarrow B$$
$$x \mapsto H(x, t)$$

---

Thm:  $A \subset \overset{\text{open}}{\mathbb{R}^n}$ ,  $B \subset \overset{\text{open}}{\mathbb{R}^m}$

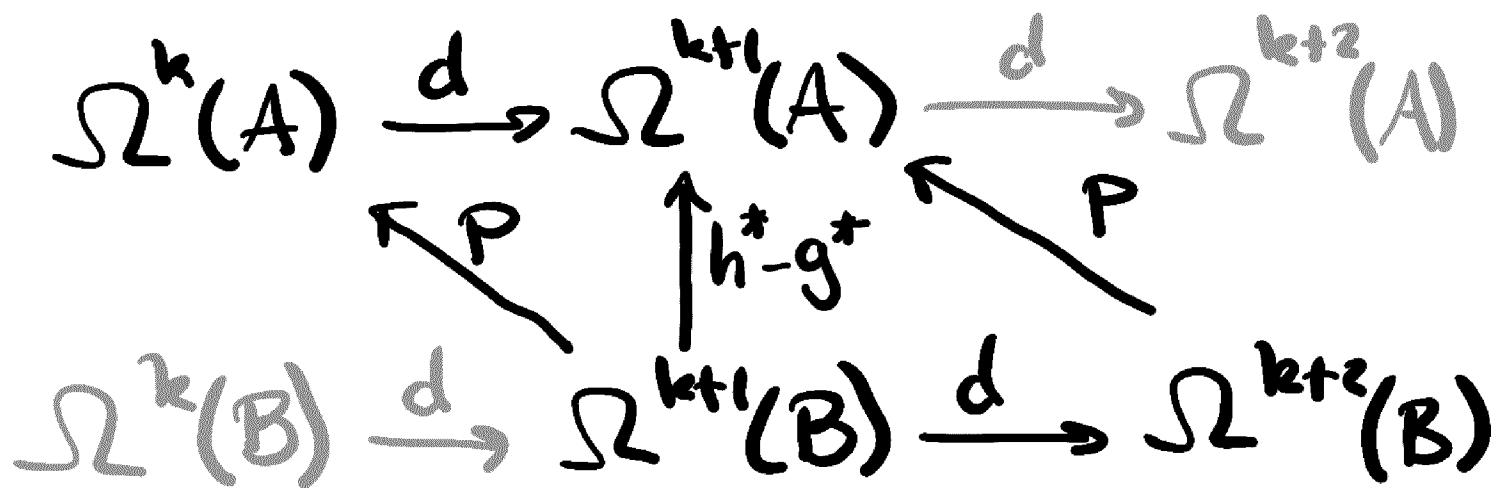
$g, h: A \rightarrow B$  smooth and homotopic.

Then  $\exists$  a linear map

$$P: \Omega^{k+1}(B) \rightarrow \Omega^k(A)$$

such that

$$dP - Pd = h^* - g^*$$

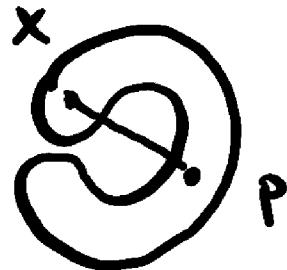


This diagram commutes.

Def: An open set  $A \subset \mathbb{R}^n$  is called star-shaped iff  $\exists$  point  $p \in A$  such that  $\forall x \in A$ , the straight line connecting  $x$  and  $p$  belongs to  $A$ .



Star-shaped



not Star-shaped

Thm (Poincaré lemma)

Let  $A \subset \overset{\text{open}}{\mathbb{R}^n}$  be Star-shaped.

If  $\omega \in \Omega^k(A)$  is closed, then it's exact.

Proof sketch: If  $A$  is Star-shaped wrt the point  $p \in A$  then we first show that the two maps

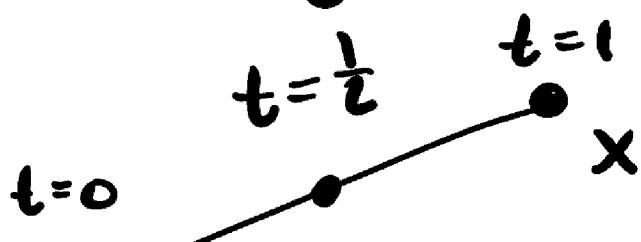
$$\begin{array}{ll} \text{id}: A \rightarrow A & c: A \rightarrow A \\ x \mapsto x & x \mapsto p \end{array}$$

are homotopic:

$$H: A \times [0,1] \rightarrow A$$

$$\begin{aligned} (x,t) &\mapsto t \text{id}(x) + (1-t)c(x) \\ &= tx + (1-t)p \end{aligned}$$

For all  $t$ , this lies on the line segment Conn.  $x$  and  $p$



Therefore if  $f \in \Omega^0(A)$   
we have

$$\begin{aligned} P(df) &= id^*f - c^*f = f \circ id - f \circ c \\ &= f - f(p) \end{aligned}$$

so if  $f$  closed we get

$$0 = f(x) - f(p) \quad \forall x \in A.$$

$\Rightarrow f$  constant on  $A$ .

Next if  $\omega \in \Omega^k(A)$  ( $k > 0$ )

$$dP\omega - Pd\omega = id^*\omega - c^*\omega \quad (t)$$

$$id^*\omega = \omega$$

$$c^*\omega = c^* \left( \sum_I \omega_I dx_I \right)$$

$$= \sum_I (\omega_I \circ c) dC_I$$

but  $dC_I = 0$  because  $C$  is the constant function.

If  $\omega$  closed we get

$d(P\omega) = \omega$  which precisely means that  $\omega$  is exact.

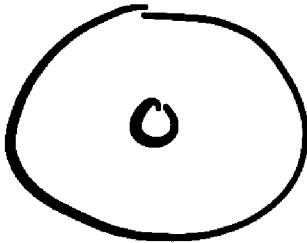
□

---

Rmk Poincaré's lemma works in greater generality than star-shaped open sets. In fact it works for any contractible open set.

(This means diffeomorphic to a ball!)

It fails e.g. for open annuli in  $\mathbb{R}^2$



## de Rham Cohomology (§40)

We have already seen previously that  $d^2 = 0$ . For each  $k \geq 0$ ,  $\Omega^k(M)$  is a vector space.

Define

$$\Omega^*(M) := \bigoplus_{k=0}^n \Omega^k(M)$$

This is also a vector space. We say that  $\Omega^*(M)$  is a graded vector space.  $\Omega^k(M) \subset \Omega^*(M)$  are the "degree"  $k$  forms.

In fact, equipping  $\Omega^*(M)$  with wedge product, defines a graded algebra.

More importantly, equipping the graded vector space  $\Omega^*(M)$  w/ the differential  $d$  defines

a cochain complex  $(\Omega^*(M), d)$

$$\Omega^0(M) \xrightarrow{d_0} \Omega^1(M) \xrightarrow{d_1} \Omega^2(M)$$

$d_2 \downarrow \dots$

$$d_{i+1} \circ d_i = 0$$

In more algebraic terms

$d^2 = 0$  is equivalent to

$\text{im } d_i \subset \ker d_{i+1}$  for all  $i$

Def: If  $C^* = \bigoplus_{i=0}^{\infty} C_i$  is a graded vector space, and

$$d_i: C_i \longrightarrow C_{i+1} \quad \forall i$$

linear map s.t.  $d_{i+1} \circ d_i = 0$ ,

the  $i$ -th cohomology group

is defined as the vector sp

$$H^i(C, d) := \ker d_i / \text{im } d_{i-1}$$

Def: The  $i$ -th de Rham cohomology group is defined as

$$H^i(\Omega^*(M), d)$$

$$= H_{dR}^i(M) := \ker d_i / \text{im } d_{i-1}$$

$$= \frac{\{\text{closed } i\text{-forms}\}}{\{\text{exact } i\text{-forms}\}}$$

---

Ex: If  $U \overset{\text{open}}{\subset} \mathbb{R}^n$  is star-shaped we have by Poincaré lemma that

- Any closed 0-form is constant (fct w/  $\frac{\partial f}{\partial x} = 0$  is const)
- Any closed  $k$ -form ( $k > 0$ ) is exact.

$H_{dR}^0(U) = \{\text{closed } 0\text{-forms}\}$  $= \{\text{constant functions}\}$  $\cong \mathbb{R} \text{ as a vector space}$  $H_{dR}^k(U) = \frac{\{\text{closed } k\text{-forms}\}}{\{\text{exact } k\text{-forms}\}} \cong 0$ 

Therefore  $H_{dR}^*(U) = \begin{cases} \mathbb{R}, & * = 0 \\ 0, & \text{else} \end{cases}$

---

Recall that if  $A \overset{\text{open}}{\subset} \mathbb{R}^n$ ,  $B \overset{\text{open}}{\subset} \mathbb{R}^m$

$g: A \rightarrow B$  smooth, then

 $g^*: \Omega^k(B) \rightarrow \Omega^k(A)$ 

commutes with  $d$ :  $g^*(d\omega) = dg^*\omega$

This realizes  $g^*$  as a "cochain map"  $g^*: \Omega^*(B) \rightarrow \Omega^*(A)$ . It's a general fact that it can be defined on the de Rham cohomology groups

 $g^*: H_{dR}^*(B) \rightarrow H_{dR}^*(A).$

Thm:  $A \overset{\text{open}}{\subset} \mathbb{R}^n$ ,  $B \overset{\text{open}}{\subset} \mathbb{R}^m$

$g: A \rightarrow B$ ,  $h: B \rightarrow A$  smooth  
such that  $h \circ g$  is homotopic  
to  $\text{id}_A$ . Then

$$H_{\text{dR}}^*(A) \cong H_{\text{dR}}^*(B)$$

---

Rmk: If  $g$  is a diffeomorphism  
then  $h = g^{-1}$  is already equal to  
 $\text{id}$ . This leads to:

$$M \cong N \Rightarrow H_{\text{dR}}^*(M) \cong H_{\text{dR}}^*(N)$$

diffeo

or equivalently

$$H_{\text{dR}}^*(M) \not\cong H_{\text{dR}}^*(N) \Rightarrow M \not\cong N$$

---

One of the most powerful  
computational tools of de Rham  
Cohomology is the Mayer-Vietoris

exact sequence.

Def: A sequence

$$0 \rightarrow U \xrightarrow{f} V \xrightarrow{g} W \rightarrow 0$$

of vector spaces is called short exact if  $f$  is injective,  $g$  is surjective and  $\text{im } f = \ker g$ .

---

Lma: Any short exact sequence

$$0 \rightarrow (U, d_U) \xrightarrow{f} (V, d_V) \xrightarrow{g} (W, d_W) \rightarrow 0$$

of cochain complexes ( $f, g$  should also commute w/ the relevant differentials) induces an exact sequence

$$0 \rightarrow H^0(U) \rightarrow H^0(V) \rightarrow H^0(W)$$

$$\hookrightarrow H^1(U) \rightarrow H^1(V) \rightarrow H^1(W)$$

$$\hookrightarrow H^2(U) \rightarrow \dots$$

---

If  $A, B \subset \overset{\text{open}}{\mathbb{R}^n}$  w/  $A \cap B \neq \emptyset$   
and  $M := A \cup B$ , then we have  
inclusions

$$U \cap V \xrightarrow{\begin{smallmatrix} i_u \\ i_v \end{smallmatrix}} U \cup V \xrightarrow{\text{incl.}} M$$

Thm (Hausdorff-Vietoris) There's a  
short exact sequence:

$$0 \rightarrow \Omega^*(M) \xrightarrow{\text{restr.}} \Omega^*(U) \oplus \Omega^*(V) \xrightarrow{f} \Omega^*(U \cap V) \rightarrow 0$$

where  $f(\omega, \tau) = \tau - \omega$ .

---

This induces a long exact sequence  
in homology:

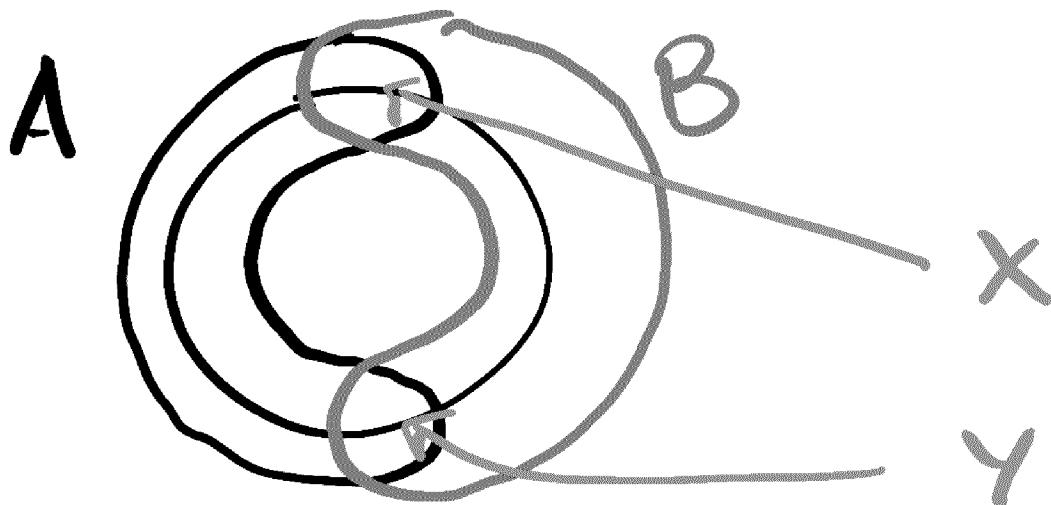
$$0 \rightarrow H_{\text{dR}}^0(M) \rightarrow H_{\text{dR}}^0(U) \oplus H_{\text{dR}}^0(V) \rightarrow H_{\text{dR}}^0(U \cap V)$$

$$\hookrightarrow H_{\text{dR}}^1(M) \rightarrow \dots$$

which is a very powerful

# Computational tool!

Ex:  $M = S^1$  unit circle in  $\mathbb{R}^2$ .



$$U = A \cap M, V = B \cap M$$

Want to compute  $H_{dR}^*(S^1)$ .

Using the more general Poincaré lemma we know

$$H_{dR}^*(U) = H_{dR}^*(V) \cong \begin{cases} \mathbb{R}, & \text{else} \\ 0, & \text{else} \end{cases}$$

$$H_{dR}^*(U \cap V) = H_{dR}^*(X \cup Y)$$

$$= H_{dR}^*(X) \oplus H_{dR}^*(Y)$$

C fact since  $X \cap Y = \emptyset$

$$\cong \begin{cases} \mathbb{R}^2, & * = 0 \\ 0, & \text{else} \end{cases}$$

since each  $x, y$  is an open interval.

$$0 \rightarrow H_{dR}^0(S^1) \rightarrow H_{dR}^0(U) \oplus H_{dR}^0(V)$$

$$\rightarrow H_{dR}^0(X) \oplus H_{dR}^0(Y) \rightarrow H_{dR}^1(S^1)$$

$$\rightarrow H_{dR}^1(U) \oplus H_{dR}^1(V) \xleftarrow{\cong} 0$$

$$\rightarrow H_{dR}^1(X) \oplus H_{dR}^1(Y) \xrightarrow{\cong} 0$$

$$0 \rightarrow H_{dR}^0(S^1) \xrightarrow{f} \mathbb{R}^2 \xrightarrow{g} \mathbb{R}^2$$

$$\xrightarrow{h} H_{dR}^1(S^1) \rightarrow 0$$

where  $f$  injective,  $h$  surjective  
 $\text{im } f = \ker g$ ,  $\text{im } g = \ker h$

Now by the rank nullity theorem.

$$\begin{aligned} H_{\text{dR}}^0(S^1) &\cong \ker f \oplus \text{im } f \\ &\cong \text{im } f \cong \ker g \end{aligned}$$

the map  $g$  is

$$g: H_{\text{dR}}^0(U) \oplus H_{\text{dR}}^0(V) \rightarrow H_{\text{dR}}^0(X) \oplus H_{\text{dR}}^0(Y)$$
$$(\omega, \tau) \mapsto (\tau - \omega, \tau - \omega)$$

these  $\xrightarrow{\text{are closed,}}$   
hence constant  
functions

$$\ker g = \{(\omega, \tau) \in H_{\text{dR}}^0(U) \oplus H_{\text{dR}}^0(V) \mid \omega = \tau\}$$

is 1-dimensional

$$\Rightarrow H_{\text{dR}}^0(S^1) \cong \mathbb{R}.$$

Rank-nullity again:

$$\ker g \oplus \text{im } g \cong \mathbb{R}^2 \Rightarrow \text{im } g \cong \mathbb{R}$$

$$\ker h \oplus \text{im } h \cong \text{im } g \oplus H^1_{\text{dR}}(S^1)$$

$$\cong \mathbb{R}^2$$

$$\Rightarrow \boxed{H^1_{\text{dR}}(S^1) \cong \mathbb{R}}$$


---

Can Show by induction  
(and similar techniques as above)

that

$$H^*_{\text{dR}}(S^n) \cong \begin{cases} \mathbb{R}, * = 0, n \\ 0, \text{ else} \end{cases}$$

So for instance

$S^n$  is not diffeomorphic to  $\mathbb{R}^n$ !

Can also Show

$$H^*_{\text{dR}}(T^2) \cong \begin{cases} \mathbb{R}, * = 0, 2 \\ \mathbb{R}^2, * = 1 \\ 0, \text{ else} \end{cases}$$

$$\Rightarrow T^2 \not\cong S^2$$