

Recall:

- $M$  compact oriented  $k$ -mfd in  $\mathbb{R}^n$

$\{\alpha_i: U_i \rightarrow V_i\}_{i \in I}$  orientation

$M \subset \bigcup_{i \in I} U_i$ . Pick p.o.u.

Wrt this cover  $\{\phi_i\}_{i=1}^N$

$\omega \in \Omega^k(M)$ , then

$$\int_M \omega = \sum_{i=1}^N \int_M \phi_i \omega$$

- Stokes thm:

$M$  cpt, oriented  $k$ -mfd

$\partial M$  equipped with the induced ori (coming from the "outward normal first"-rule)

$\omega \in \Omega^{k-1}(M)$

$$\int_M d\omega = \int_{\partial M} \omega$$

Recall  $I^k = [0,1]^k \subset \mathbb{R}^k$

$$\text{int } I^k = (0,1)^k$$

$$\partial I^k = I^k \setminus \text{int } I^k$$

Lma  $k > 1$

Let  $I^k \subset U \subset \mathbb{R}^k$ ,  $\eta \in \Omega^{k-1}(U)$

Assume  $\eta(x) = 0$  for  $x \in \partial I^k$   
unless  $x \in \text{int } I^{k-1} \times \{0\}$ .

$$\int_{\text{int } I^k} d\eta = (-1)^k \int_{\text{int } I^{k-1}} b^* \eta$$

$$b: I^{k-1} \longrightarrow I^k$$

$$(x_1, \dots, x_{k-1}) \mapsto (x_1, \dots, x_{k-1}, 0)$$

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Proof: Step 1:  $\int_{\text{int } I^k} d\eta = (-1)^k \int_{I^{k-1}} f \circ b$

Claim:

$$(-1)^k \int_{I^{k-1}} f \circ b = (-1)^k \int_{I^{k-1}} b^* \eta$$

Proof of claim:

$$\begin{aligned} b^* \eta &= b^*(f dx_{I_j}) \\ &= b^*(f dx_1 \wedge \dots \wedge \widehat{dx_j} \wedge \dots \wedge dx_k) \\ &= (f \circ b) (\det Db_{I_j}) db_1 \wedge \dots \wedge \widehat{db_j} \wedge \dots \wedge db_k \end{aligned}$$

$$Db = \begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \\ 0 & \dots & 0 \end{pmatrix}$$

$$\text{So } \det Db_{I_j} = \begin{cases} 0 & j < k \\ 1 & j = k \end{cases}$$

$$\begin{aligned} \Rightarrow b^* \eta &= (f \circ b) db_1 \wedge \dots \wedge \widehat{db_k} \\ &= (f \circ b) du_1 \wedge \dots \wedge du_{k-1} \end{aligned}$$

□

Thm  
 $k > 1$

$M$  cpt oriented  $k$ -mfed  
in  $\mathbb{R}^n$ . Assume  $\partial M$  is given  
the induced orientation if its  
non-empty.

$$M \subset U \subset \mathbb{R}^n, \omega \in \Omega^k(U)$$

$$\int_M d\omega = \int_{\partial M} \omega \quad \text{if } \partial M \neq \emptyset$$

$$\left( \int_M d\omega = 0 \quad \text{if } \partial M = \emptyset \right)$$

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The essence of the theorem was  
already seen when we proved it  
for cubes. We sketch the general  
proof.

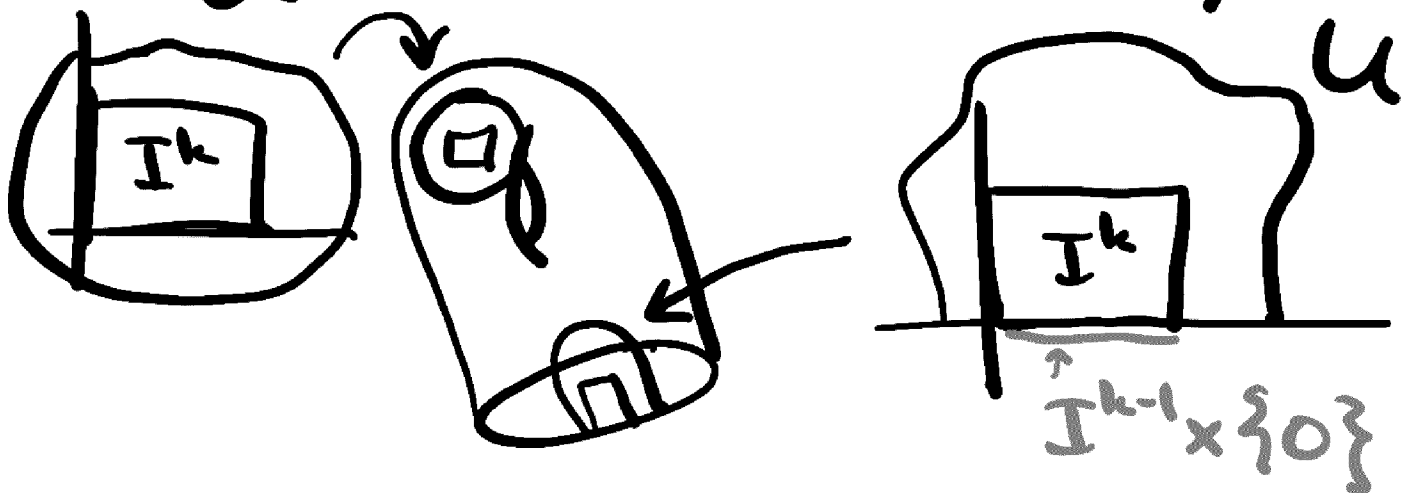
Proof sketch:

① Possibly after rescaling/translation  
we can assume that every  
coord chart

$\alpha: U \rightarrow V$  is so that

★  $I^k \subset U$  and

★  $I^{k-1} \times \{0\} \subset U \cap \partial H^k$   
 (if  $U \subset^{\text{open}} H^k$ )



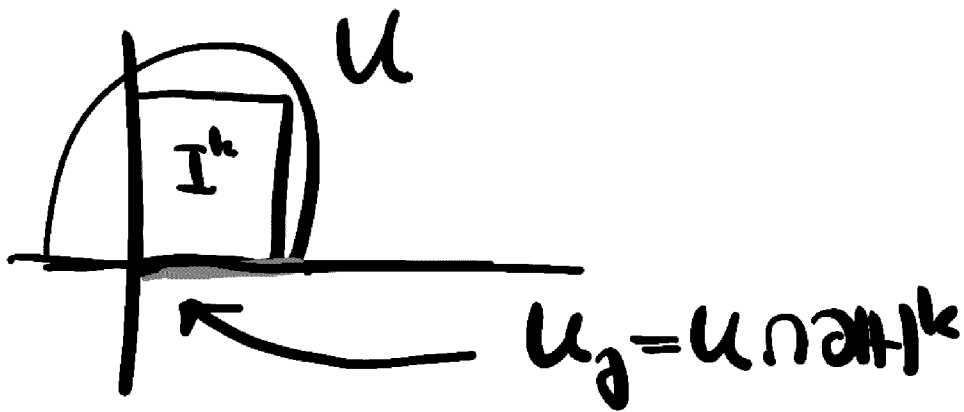
By linearity of integrals,  $d$  and pullbacks, it suffices again to prove it for  $\omega = f dx_{I_j}$ .

For a chart  $u: U \rightarrow V$   
 around  $x \in \partial M$

$$\int_{U, \alpha} d\omega = \int_{\text{int } I^k} d(f dx_{I_j})$$

$$= (-1)^k \int_{\text{int } I^{k-1}} b^*(f dx_{I_j})$$

Previous  
 thm



$$I^{k-1} \subset U_g \stackrel{\text{open}}{\subset} \mathbb{R}^{k-1}.$$

Let  $\beta: U_g \rightarrow V_g$ ,  $V_g = V \cap \partial M$  be the restricted coord chart. Now, by def  $\beta$  belongs to the induced ori on  $\partial M$  if  $k$  is even; else if  $k$  is odd we have to take the opposite ori. This leads to

$$\int_{U_g, \beta} \omega = (-1)^k \int_{\text{int } I^{k-1}} \beta^* \omega = \int_{U, \alpha} d\omega$$

ori reversal  
due to dim

Previous  
calculation

Now patch everything together with a partition of unity

$$\rightsquigarrow \int_M d\omega = \int_{\partial M} \omega$$

□

Remark: • We excluded the  $k=1$  case for simplicity, because we have not discussed orientations on 0-manifolds (= discrete set of points)

• An orientation on a 0-manifold  $M$  is a function

$$E: M \rightarrow \{\pm 1\}.$$

• If  $M$  is an oriented manifold with boundary, then the induced orientation is as follows:

"outward normal"



# Vector calculus

## Thm (Divergence theorem)

Let  $M$  be a compact  $n$ -mfd w/  $\partial$  in  $\mathbb{R}^n$ . Suppose  $M \subset U \subset \mathbb{R}^n$  and  $U$  is open and  $G$  is a v.f. on  $U$ . Let  $N$  be the outwards pointing normal vector field to  $M$ , along  $\partial M$ . Then

$$\int_M \operatorname{div} G \, dV = \int_{\partial M} \langle G, N \rangle \, dV$$

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Proof: Given the v.f.  $G$  we def an  $(n-1)$ -form by

$$\omega = \sum_{i=1}^n (-1)^{i-1} G_i \, dx_1 \wedge \dots \wedge \widehat{dx}_i \wedge \dots \wedge dx_n$$

↑ components of  $G$

This is  $\beta_{n-1} G$  where

$\beta_{n-1}$ : vector fields  $\rightarrow$   $(n-1)$ -forms

that we saw in L21



Then wlog assume  $\partial M$  is covered by a single coord chart  $\alpha: U \rightarrow U$  (else use a partition of unity + linearity)

$$\int_{\partial M} \omega = \int_U \alpha^* \omega$$

$$= \sum_{i=1}^n (-1)^{i+1} \int_U (G_i; \circ \alpha) \det \frac{\partial (\alpha_1, \dots, \hat{\alpha}_i, \dots, \alpha_n)}{\partial (x_1, \dots, \hat{x}_i, \dots, x_n)} (+)$$

The rest is linear algebra:

If  $v_1, \dots, v_{n-1}$  are lin indep vectors in  $\mathbb{R}^n$   
let  $i \in \{1, \dots, n-1\}$  & def

$$X_i := [v_1 \dots v_{n-1}] \text{ w/ row } i \text{ removed}$$

$$\text{Then } C = \sum_{i=1}^n C_i e_i$$

$$C_i = (-1)^{i-1} \det X_i$$

is s.t.  $(C, v_1, \dots, v_{n-1})$  is a right-handed basis of  $\mathbb{R}^n$ , and

$$\|C\| = V([v_1 \dots v_{n-1}])$$

Back to (†) we have that

$$C = \sum_{i=1}^n (-1)^{i+1} \det \frac{\partial (\alpha_1, \dots, \hat{\alpha}_i, \dots, \alpha_n)}{\partial (x_1, \dots, \hat{x}_i, \dots, x_n)} \partial_i$$

is the outwards normal. So

$$N(\alpha(x)) = \left( \alpha(x), \frac{C(x)}{\|C(x)\|} \right)$$

$$\int_{\partial M, \alpha} \langle G, N \rangle dV = \int_U \langle G \circ \alpha, N \circ \alpha \rangle V(D\alpha)$$

$$= \int_U \left\langle G \circ \alpha, \frac{C}{\|C\|} \right\rangle \|C\| = \int_U \langle G \circ \alpha, C \rangle$$

$$= \int_U \sum_{i=1}^n (-1)^{i+1} (G_i \circ \alpha) \det \frac{\partial (\alpha_1, \dots, \hat{\alpha}_i, \dots, \alpha_n)}{\partial (x_1, \dots, \hat{x}_i, \dots, x_n)}$$

Next by Stokes theorem

$$\int_{\partial M} \omega = \int_M d\omega, \text{ and we know}$$

from a previous calculation  
(see L21) that

$$d\omega = (\operatorname{div} G) dx_1 \wedge \dots \wedge dx_n$$

□

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