

MAT 531

Geometry/Topology II

Introduction to Smooth Manifolds

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May 5, 2020

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$$H^k(M) := \frac{\ker d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)}{\text{Image } d : \Omega^{k-1}(M) \rightarrow \Omega^k(M)}$$

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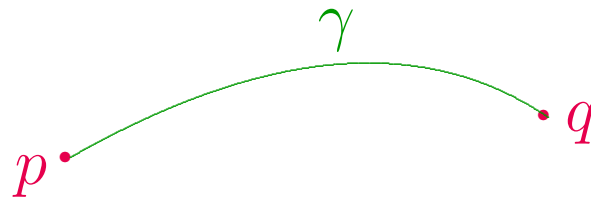
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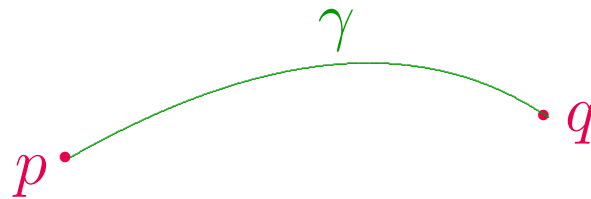
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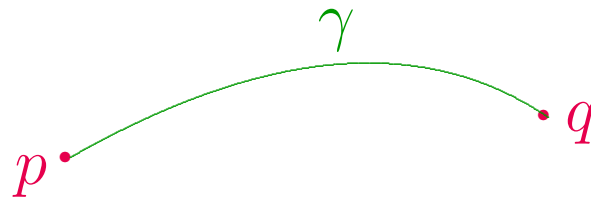
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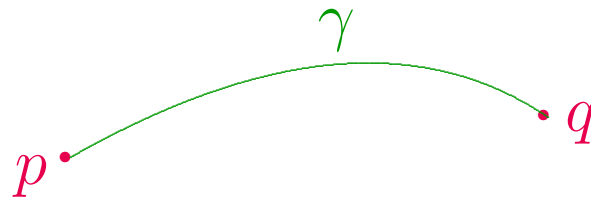
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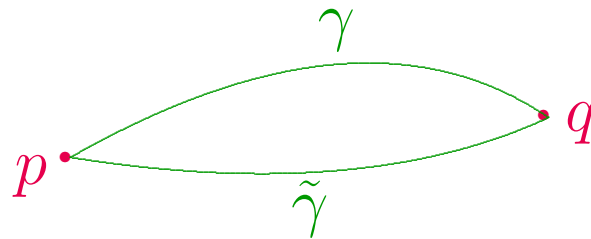
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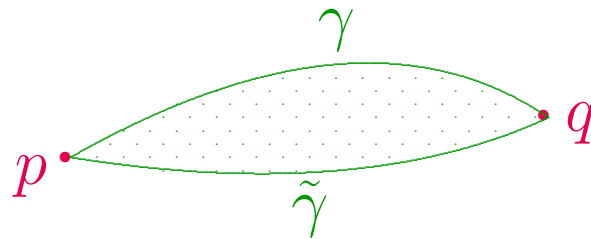
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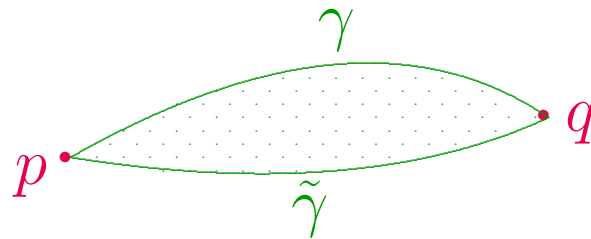
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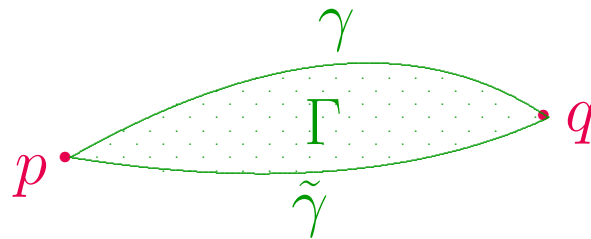
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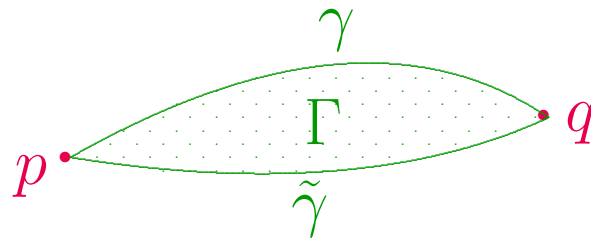
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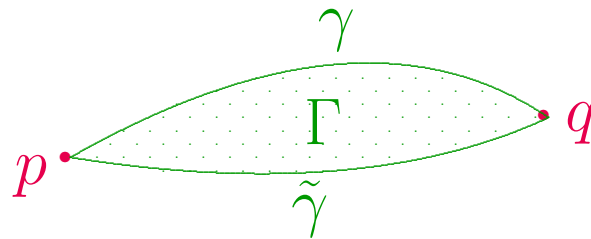
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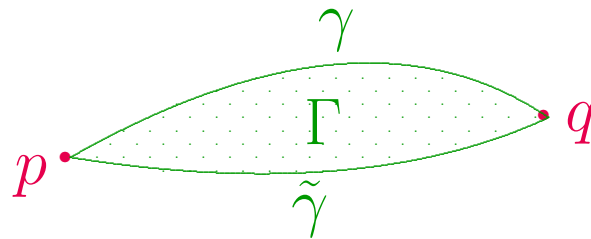
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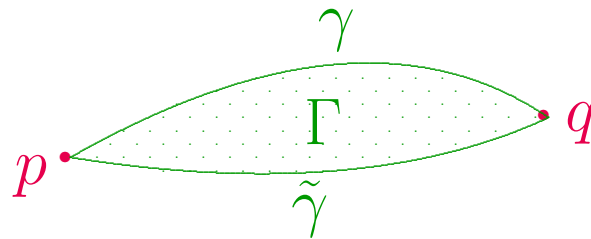
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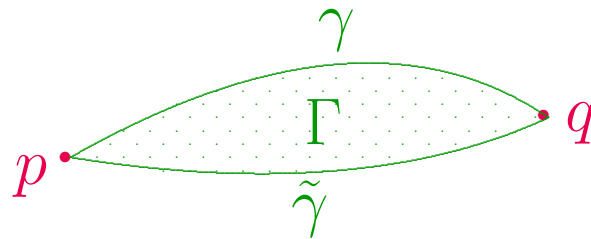
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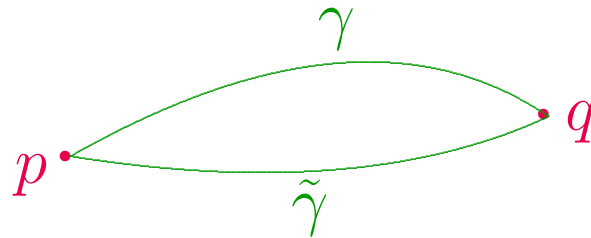
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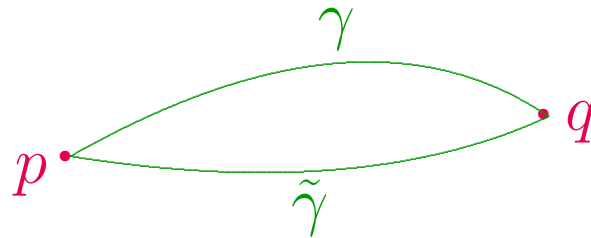
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The homotopy invariance of the degree is actually symptomatic of a more general principle. . .

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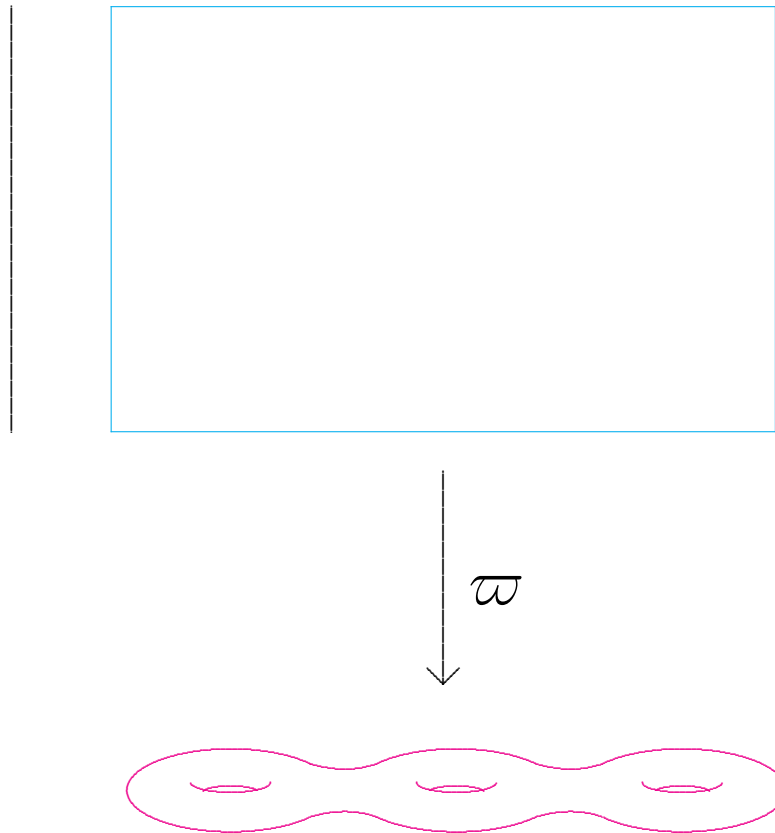
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Proposition. *The first-factor projection*

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Cartan's Magic Formula: If $\varphi \in \Omega^k(M)$, then, for any $V \in \mathfrak{X}(M)$, then

$$\mathcal{L}_V \varphi = V \lrcorner d\varphi + d(V \lrcorner \varphi).$$

When φ is closed:

$$\mathcal{L}_V \varphi = d(V \lrcorner \varphi).$$

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One of the best basic tools is the following...

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Exact: Kernel = Image at every stage.

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 & & \vdots & & \vdots & & \vdots \\
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Commutative diagram with exact rows!

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 0 & \rightarrow & \Omega^{k-1}(\mathcal{U} \cup \mathcal{V}) & \rightarrow & \Omega^{k-1}(\mathcal{U}) \oplus \Omega^{k-1}(\mathcal{V}) & \rightarrow & \Omega^{k-1}(\mathcal{U} \cap \mathcal{V}) \rightarrow \\
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 \end{array}$$

“Snake Lemma:” Induces long exact sequence...

$$\begin{array}{ccccccc}
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& & & & \delta & & \\
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& & & & & & \\
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Mayer-Vietoris long exact sequence therefore reads...

$$0 \longrightarrow H^0(S^n) \longrightarrow H^0(\mathbb{R}^n) \oplus H^0(\mathbb{R}^n) \longrightarrow H^0(S^{n-1} \times \mathbb{R})$$

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Proposition.

$$H^k(S^n) = \begin{cases} \mathbb{R} & \text{if } k = 0 \text{ or } n, \\ 0 & \text{otherwise.} \end{cases}$$

Finally, let's shore up our foundations...

De Rham Cohomology:

$$H^k(M) := \frac{\{\text{closed } k\text{-forms}\}}{\{\text{exact } k\text{-forms}\}}$$

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That is, an n -form is exact iff its integral = 0.

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Same conclusion if M compact manifold-with-boundary, where $\partial M \neq \emptyset$.

Compactly supported cohomology.

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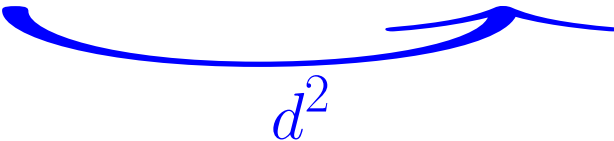
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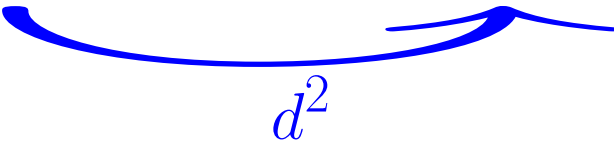
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A blue curved arrow points from the $\Omega_c^k(M)$ term to the $\Omega_c^{k+1}(M)$ term in the sequence above. Below the arrow is the label d^2 .

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$$H_c^k(M) := \frac{\ker d : \Omega_c^k(M) \rightarrow \Omega_c^{k+1}(M)}{\text{Image } d : \Omega_c^{k-1}(M) \rightarrow \Omega_c^k(M)}$$

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Now proceed by induction...

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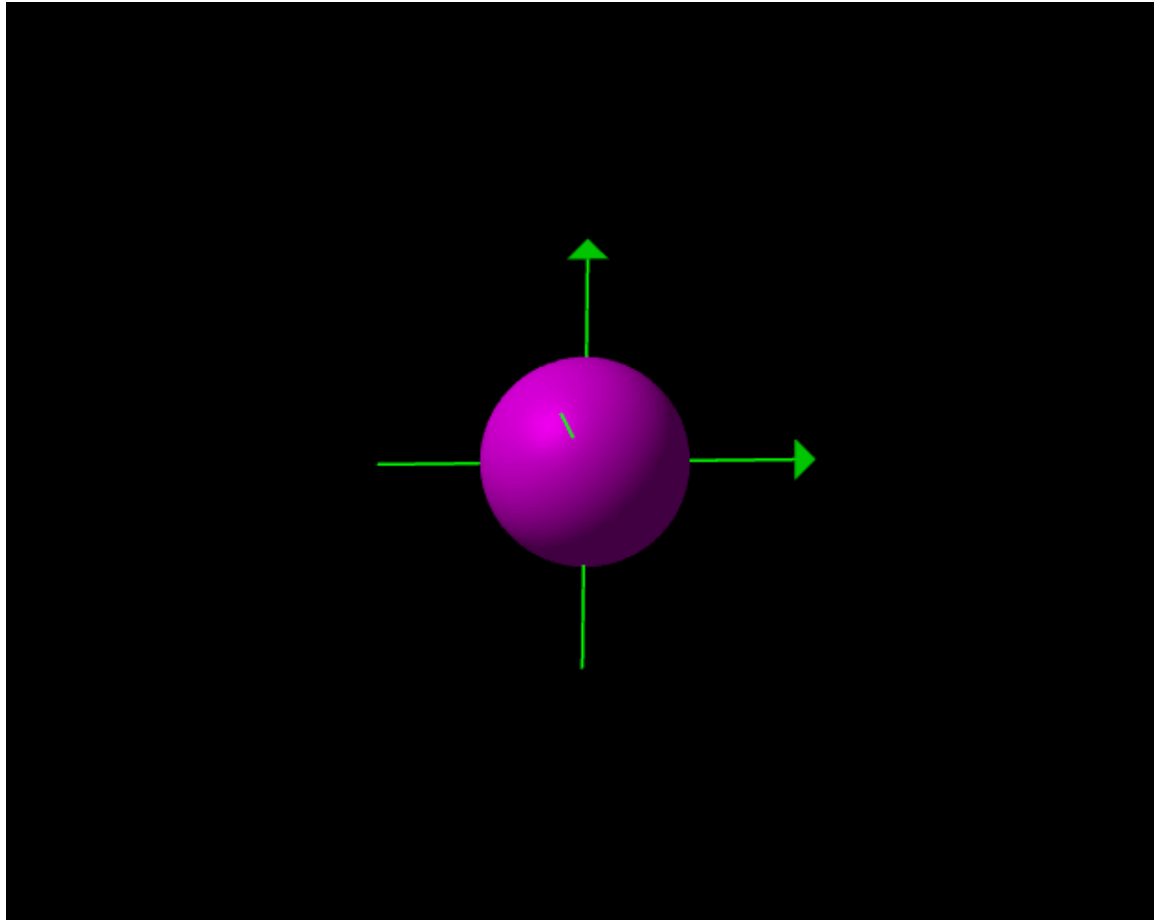
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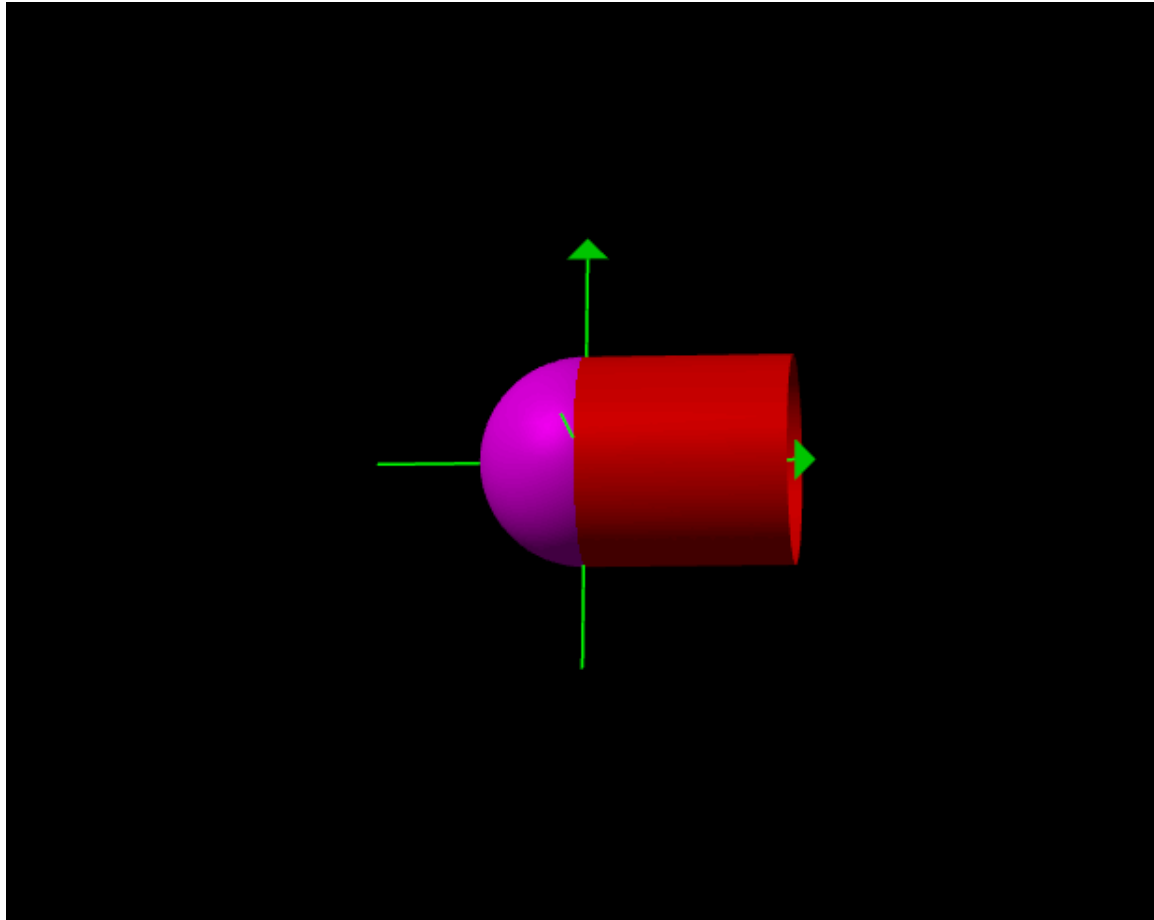
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Support of φ :



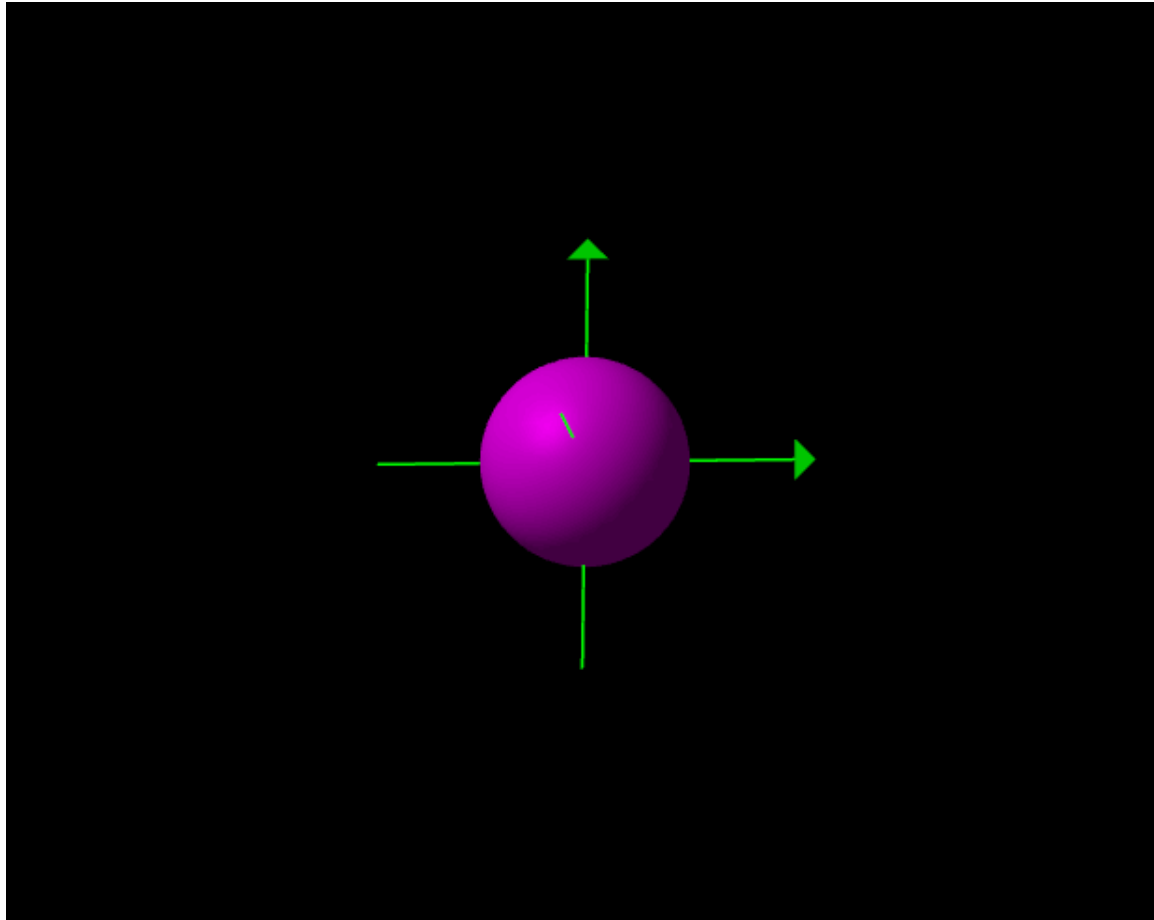
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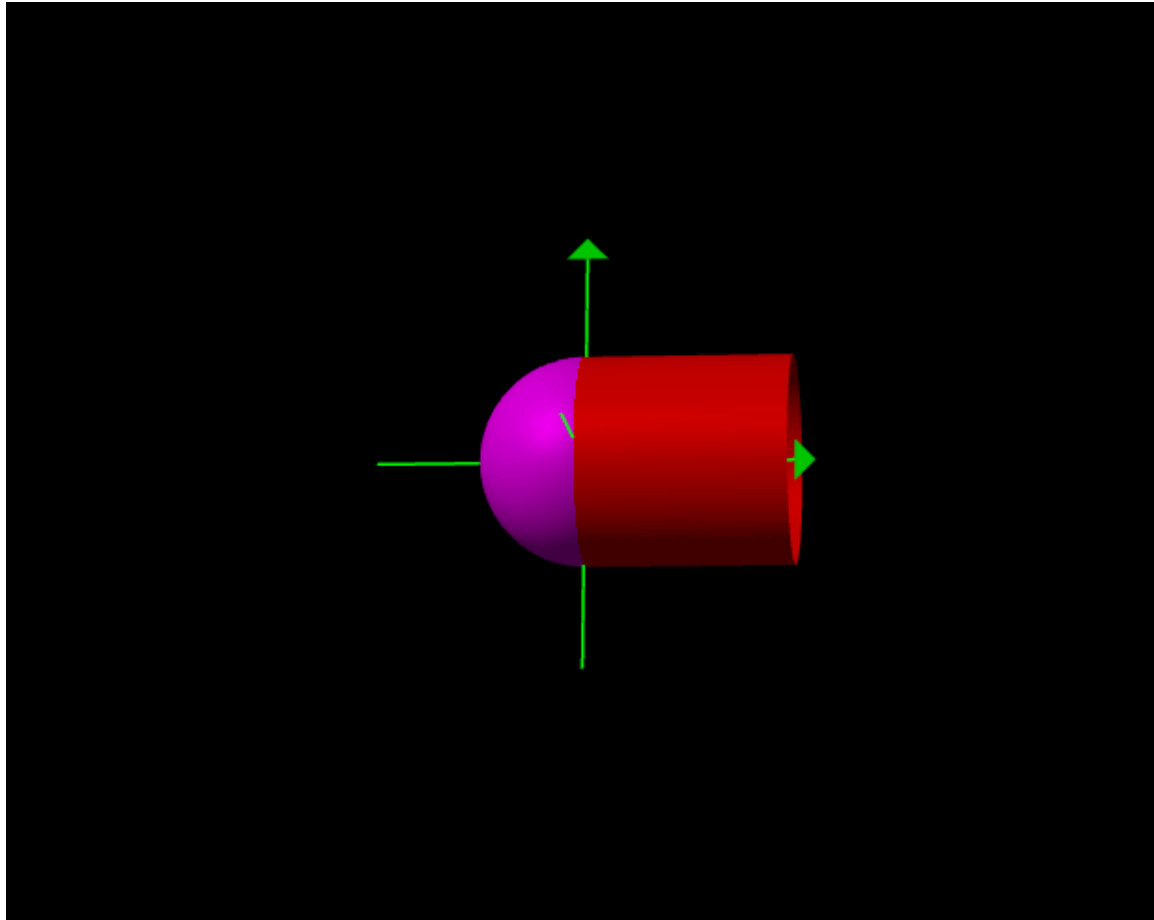
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Notation:

$$\begin{aligned} \pi : \mathbb{R}^n &\longrightarrow \mathbb{R}^{n-1} \\ (x^1, x^2, \dots, x^n) &\longmapsto (x^2, \dots, x^n) \end{aligned}$$

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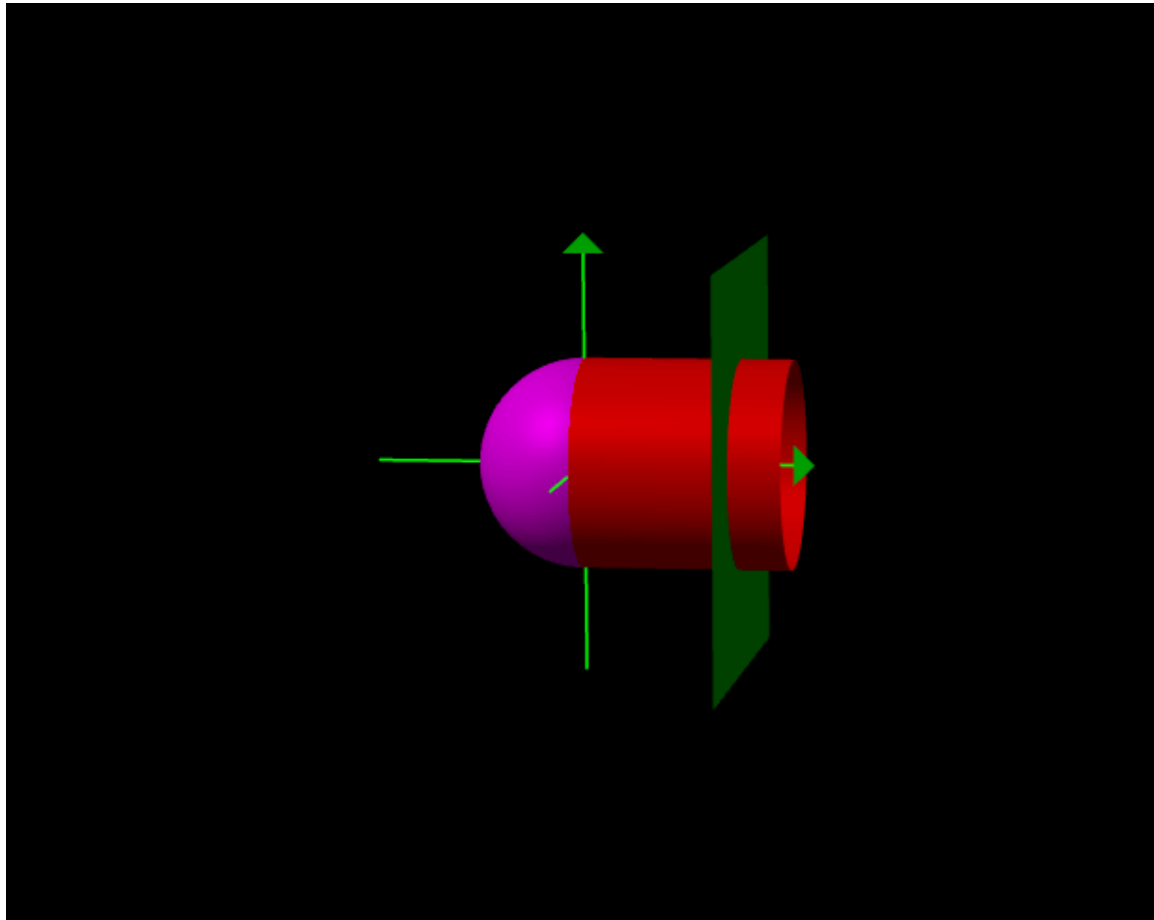
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Reduction to \mathbb{R}^{n-1} :



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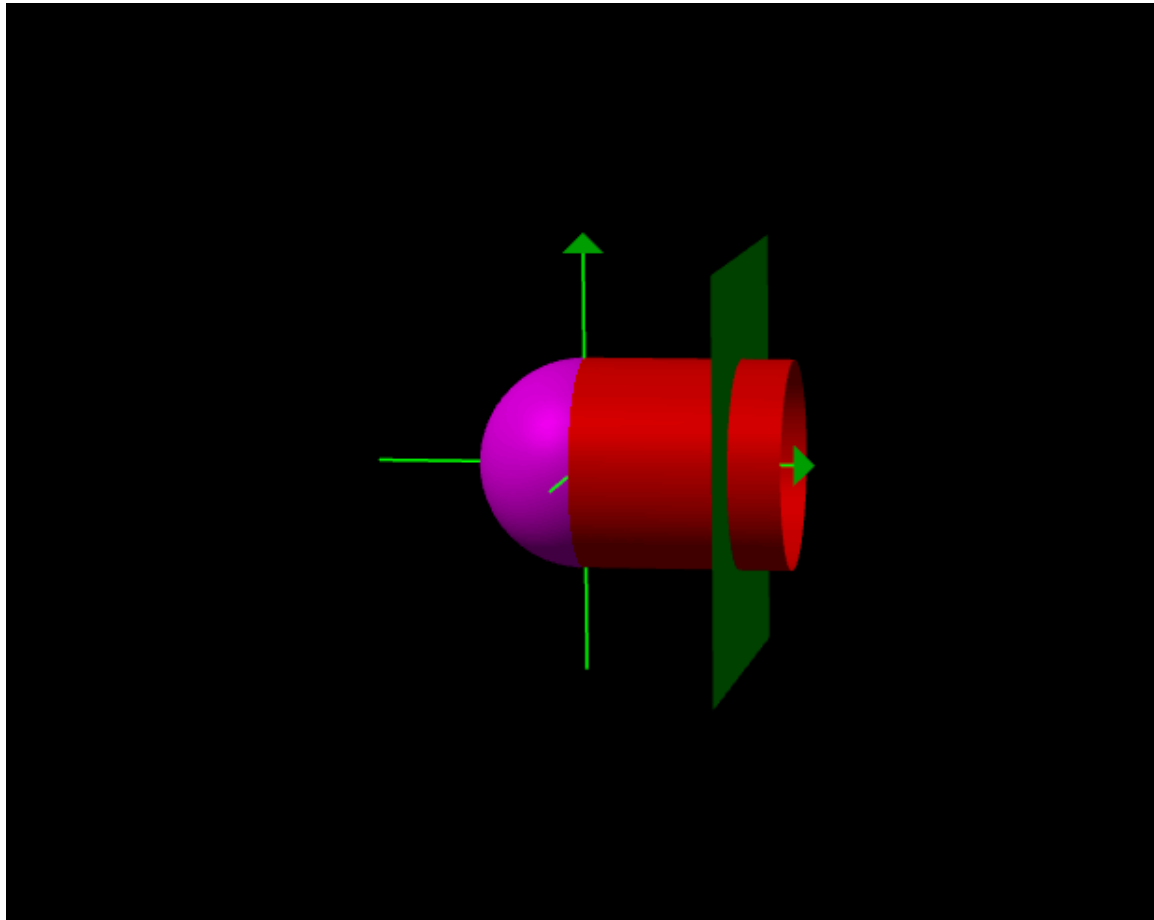
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Reduction to \mathbb{R}^{n-1} :



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A graph of a smooth transition function. The function is zero for negative values of x and one for positive values of x. The transition from 0 to 1 is smooth and occurs around x=0. The graph is drawn in a light purple color.

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Proposition. Let $\varphi \in \Omega_c^n(\mathbb{R}^n)$ be a compactly supported n -form with

$$\int_{\mathbb{R}^n} \varphi = 0.$$

Then

$$\varphi = d\psi$$

for some compactly supported form $\psi \in \Omega_c^{n-1}(\mathbb{R}^n)$.

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Using this, we now prove a major generalization...

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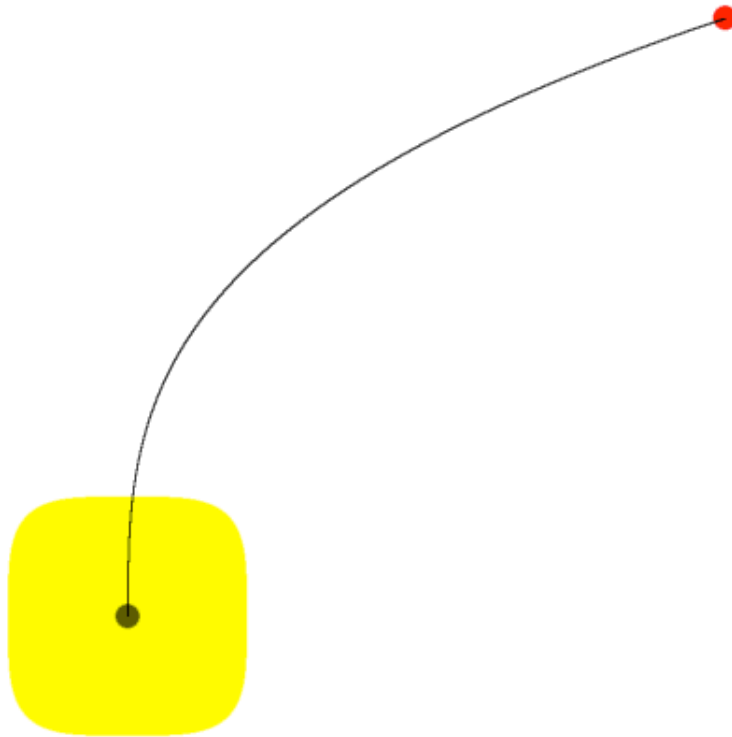
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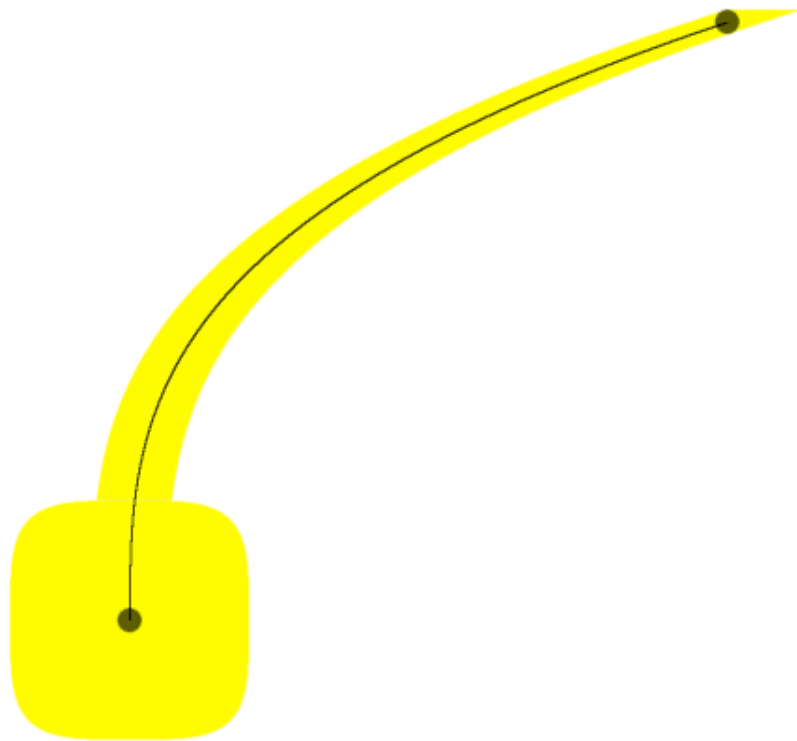
Now recall an application of flow of a vector field...

Lemma. Let M^n be a smooth connected n -manifold, and let $p, q \in M$ be any two points. Then M contains a coordinate domain $\mathcal{U} \approx \mathbb{R}^n$ such that $p, q \in \mathcal{U}$.

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$$\varphi_j = f_j \varphi, \quad j = 1, \dots, \ell.$$

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Then each n -forms φ_j is then compactly supported in \mathcal{U}_j , and

$$\varphi = \varphi_1 + \dots + \varphi_\ell.$$

Now set $\mathcal{V} := \bigcap_{j=1}^{\ell} \mathcal{U}_j$.

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This now implies...

Theorem. *If M^n is a **connected**, oriented smooth n -manifold (without boundary), then*

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Specializing to the compact case, we thus have...

Theorem. *If M^n is a smooth compact, connected, oriented n -manifold (without boundary), then*

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By contrast...

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To see this, first recall...

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$$\Phi^2 = \text{identity}.$$

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Same trick used in non-compact case...

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Deduce non-orientable case by our double-cover trick.